



The Highlanders

Electronics Board design

Spotlight - 4499's Upside down design

These ideas are team 4499's tips and ideas...they are by no means the "best" out there!

Introductions

The Highlanders

Who are we?

- Community based team
- From 5 different schools
- Starting our 9th FRC season

Presenting today:

Cooper Ward - 4 years in FRC

Alex Torres - 2 years in FRC

Hailey Holman - 2 years in FRC

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How 4499 designs and implements electronic layouts

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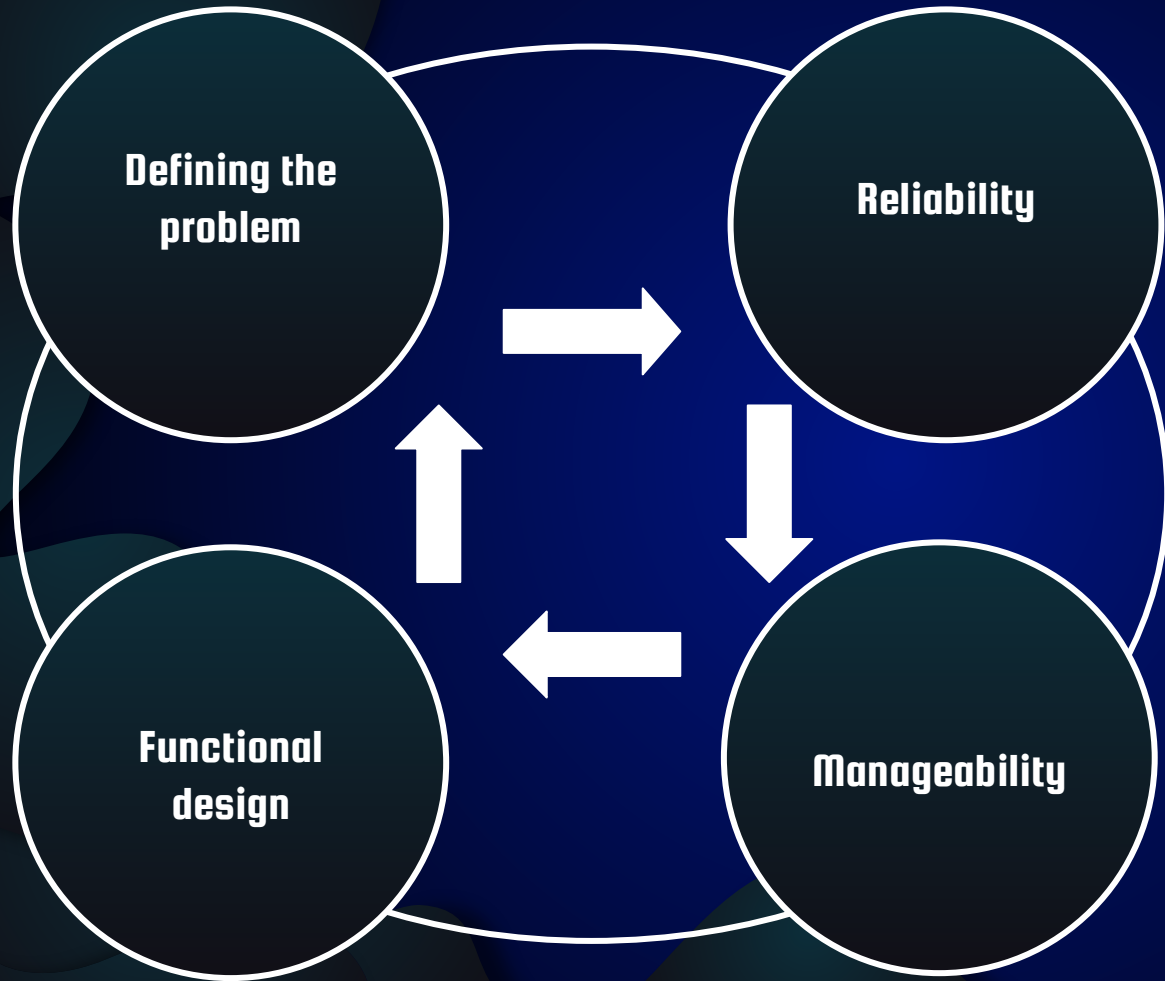
Turn the board, upside-down!

06 Troubleshooting & Lessons Learned

Things we have learned the hard way

Goals

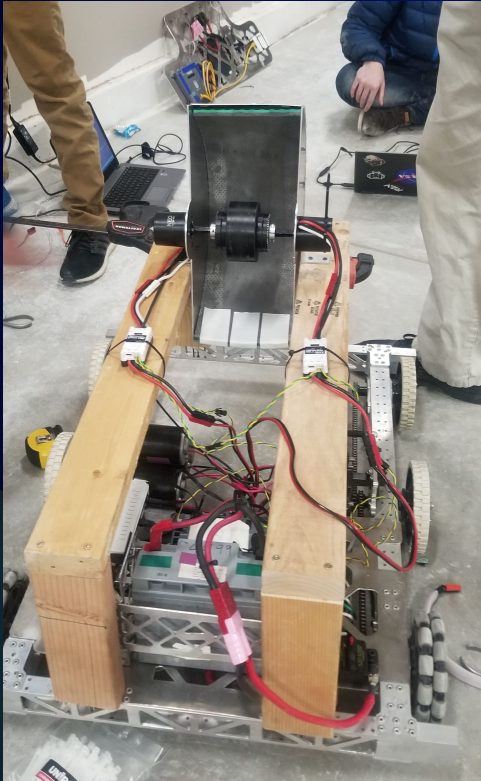
of electrical design



4499 Goals of Electrical Design

Defining the problem

How are we going to design an electronics layout without a complete robot design build?



- **General idea layouts**
 - PDP Centered
 - Battery COG
- **Chassis design**
 - Chain in tube?
 - WCD layout?
- **Location of specific things**
 - Router position
 - Cameras? Type of cameras
- **Motors**
 - Controllers? NEOS/Falcons
- **Number of motors**
 - Power Budget (next slide)
 - Motor controllers/Falcons?
- **Pneumatics?**
 - Space
 - PCM slots

Power Budget

WITH PNEUMATICS			VRM 1	Note: we can get away with 1 VRM if we have a 20 amp spot somewhere else? Add Pneumatics on this spread sheet	
PDP	USED BY		SLOTS	USED BY	
1 (40 amp)	Falcon 500 1	Drive Train	12v/2a	RADIO	
2 (40 amp)	Falcon 500 2	Drive Train	12v/2a		
3 (40 amp)	Falcon 500 3	Drive Train	12v/500ma	LED LIGHT RINGS	
4 (40 amp)	Falcon 500 4	Drive Train	12v/500ma	Jevois PowerBuck 1	
5 (40 amp)	Falcon 500 5	Flywheel	5v/2a	BLINKIN LED DRIVER	
6 (40 amp)	Falcon 500 6	Flywheel	5v/2a	Blinkin LED DRIVER 2	
7 (40 amp)	Neo 1/Falcon 50 Arm		5v/500ma		
8 (40 amp)	Neo 2	Climber Winch	5v/500ma		
9 (30 amp)	Neo 550 1	Intake	12Vin	PDP	
10 (30 amp)					
11 (30 amp)	BAG 1	Magazine		VRM 2	
12 (30 amp)	775Pro 1	Magazine		SLOTS	
13 (30 amp)	Neo 550 5	Indexer	12v/2a	USED BY	
14 (30 amp)	Neo 550 6	Hood	12v/2a		
15 (30 amp)			12v/500ma	LED LIGHT RINGS	
16 (30 amp)			12v/500ma		
			5v/2a		
VRM PWR	VRM 1	VRM 2	5v/2a		
PCM PWR	PCM		5v/500ma		
Roborio PWR	RoboRio		5v/500ma		
			12Vin	PDP	

NO PNEUMATICS			VRM 1		
PDP	USED BY		SLOTS	USED BY	
1 (40 amp)	Falcon 500 1	Drive Train	12v/2a		
2 (40 amp)	Falcon 500 2	Drive Train	12v/2a	RADIO	
3 (40 amp)	Falcon 500 3	Drive Train	12v/500ma	LED LIGHT RINGS	
4 (40 amp)	Falcon 500 4	Drive Train	12v/500ma	PowerBuck 1	
5 (40 amp)	Falcon 500 5	Flywheel	5v/2a	BLINKIN LED DRIVER	
6 (40 amp)	Falcon 500 6	Flywheel	5v/2a	Blinkin LED DRIVER 2	
7 (40 amp)	Neo 1	Climber arm	5v/500ma		
8 (40 amp)	Neo 2	Climber Winch	5v/500ma		
9 (30 amp)	Neo 550 1	Intake	12Vin	PDP	
10 (30 amp)	Neo 550 2	Intake			
11 (30 amp)	Neo 550 3	Magazine		VRM 2	
12 (30 amp)	Neo 550 4	Magazine		SLOTS	
13 (30 amp)	Neo 550 5	Indexer	12v/2a	Jetson Nano	
14 (30 amp)	Neo 550 6	Hood	12v/2a	Realsense	
15 (30 amp)	Neo 550 7	Spinner	12v/500ma	Powerbuck 2	
16 (30 amp)	Neo 550 8	Spinner	12v/500ma	2nd Je Vois Vision Camera	
NO SLOT	Neo 550 9	Leveler	5v/2a		
			5v/2a		
VRM PWR	VRM 1	VRM 2	5v/500ma		
PCM PWR	PCM		5v/500ma		
Roborio PWR	RoboRio		12Vin	PDP	
RELAY					
SLOTS	USED BY				
	1	Jetson Nano			
	2				
	3				



PCM	Mechanism/Conne
Port 0	Ratchet/Brake
Port 1	Ratchet/Brake
Port 2	Climber Deploy
Port 3	Climber Deploy
Port 4	
Port 5	
Port 6	
Port 7	
Pressure Sw.	Pressure Switch
Compressor out	Compressor
CAN	To motor controllers
Vin	PDP



Reliability

- Secured
 - Sheathing
 - Cable Chain
- Easy to maintain
 - Quick replacement
- Test wires/connection
 - Pull/tug

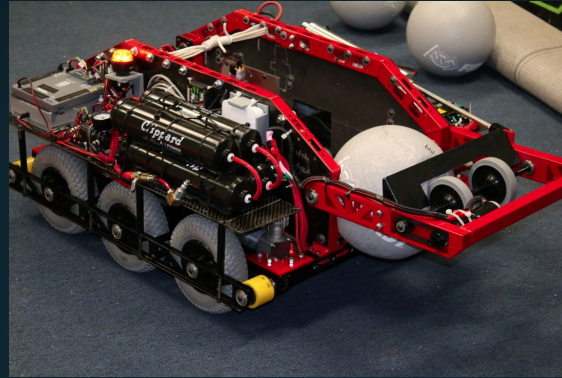
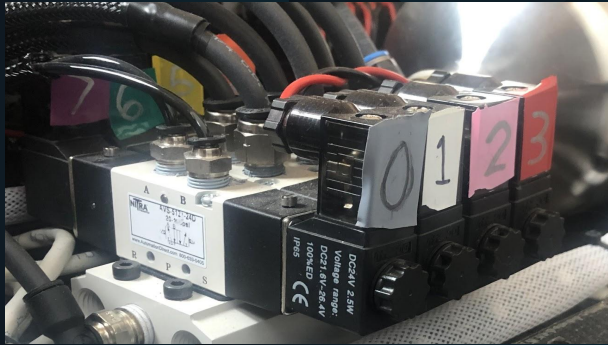
2018 - Lesson Learned:

“Dont underestimate a simple design that never breaks down”....

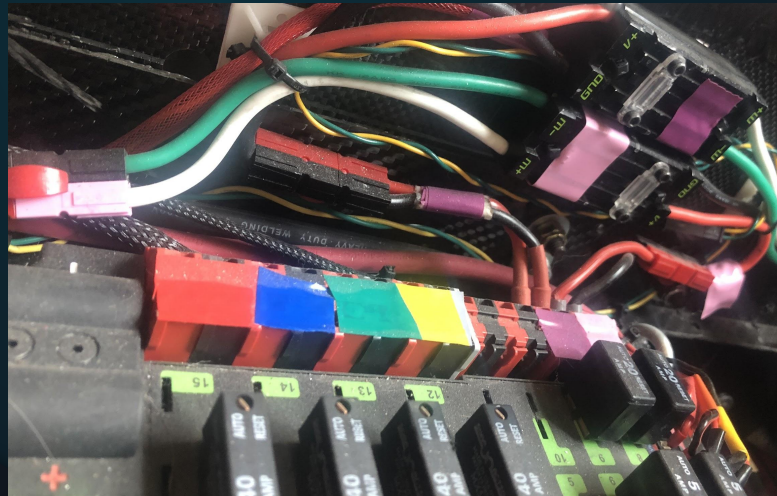
As a team we all learned this and made this a requirement for future robot designs.



Manageability

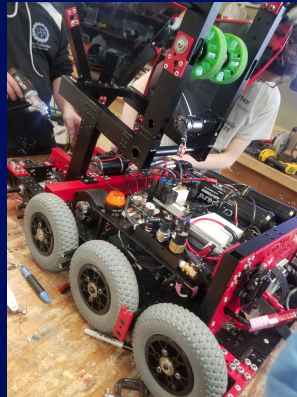
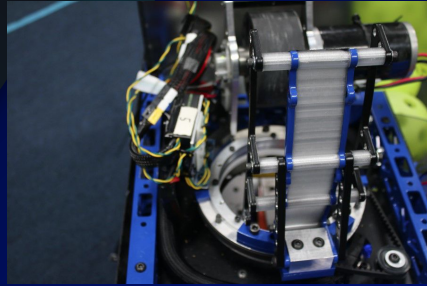


- How to find problems
- Label wires
- Color code the motors
 - PDP to motor
 - Solenoid to piston
- Route wires
- Do not make large bundles of wires



Functional Design

- Shooter with flywheel
 - Vibrations
 - Wires not near wheel/chain
- Multidirectional arm
 - Wire movement
 - Cable chain
 - Works well when repetitive motion are in place, and a single direction
- Climber
 - Movement up and down
 - Sensor placement



- Storage (of game elements)
 - Space for storage of those pieces.
 - Sensor placement
 - Analog sensor wires near motors can cause interference
 - NavX near motors can also cause interference
- Elevator
 - Movement up and down
 - Sensors placement



"I swear, if I see another one of you grabbing a battery by its cables I will smite you."

— **Cooper Ward**

Constraints

Rules, Design, Team imposed

CONSTRAINTS: TYPES



Rules - Game Manual

Rule imposed restrictions are the easiest to find (because they are written down for you)



Design

Just because you are allowed to do it within the rules, is there a reason to do it?



Team Imposed

You have found a solution that satisfies the rules, and the design of the robot. But, are there any team imposed restrictions that nullify that solution?

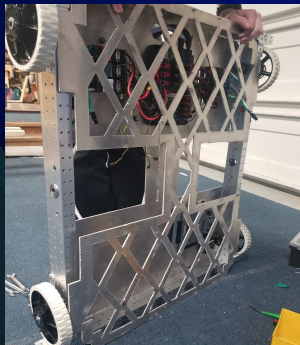
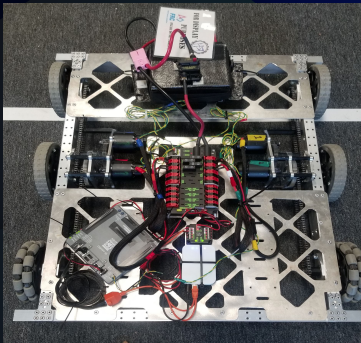
CONSTRAINTS: RULES

Rule constraints are easy to identify, here are some examples:

- R64 *The Wireless Bridge must be mounted on the ROBOT such that the diagnostic lights are visible to ARENA personnel.*
- R65A RSL . *mounted on the ROBOT such that it is easily visible while standing 3 ft. (~ 100 cm) in front of the ROBOT,*
- R43 *The 120A circuit breaker must be quickly and safely accessible from the exterior of the ROBOT. This is the only 120A circuit breaker allowed on the ROBOT.*

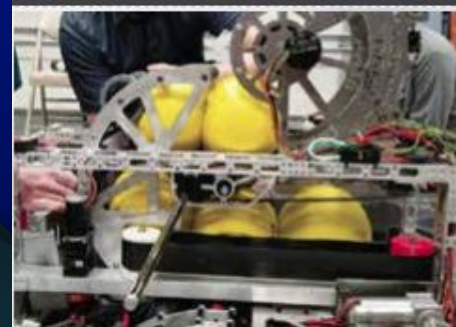
Rules change from year to year, even in electronics! What once had to be restrictive, might now be more forgiving with its placement.

How you work within these constraints is up to you, they are non-negotiable requirements for certain components.



CONSTRAINTS: Design

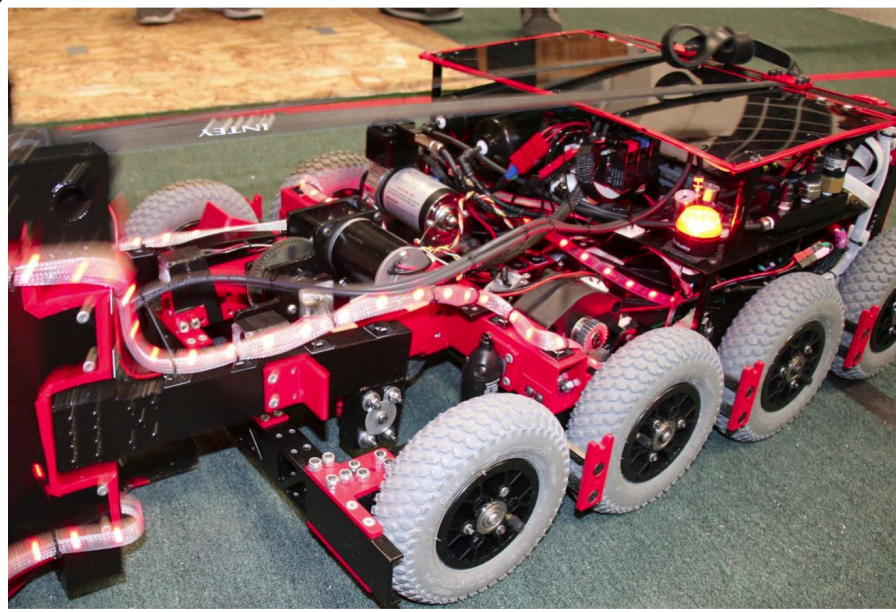
- Wireless radio
 - Highest place on robot
- Battery cables
 - Smallest run of cables
- Roborio
 - Accessible location
- How to protect components
 - Router/RoboRio/Camera
 - Bottom of robot
 - Secure battery
 - Avoid having other wires near your battery, as it can crush other cables.



CONSTRAINTS: Team Design/Robot Design



So...you just designed where all components are placed and the mechanical team decides to place the shooter right in the middle of your layout...and they see no problem with that...



- Be flexible :)
- Be willing to move everything around if needed
- Communicate
- Defend your space!
- CAD your layout and integrate within subteams
 - Main components
 - Wires not necessary
- Leverage changes positively

“AA!!!!!!!”

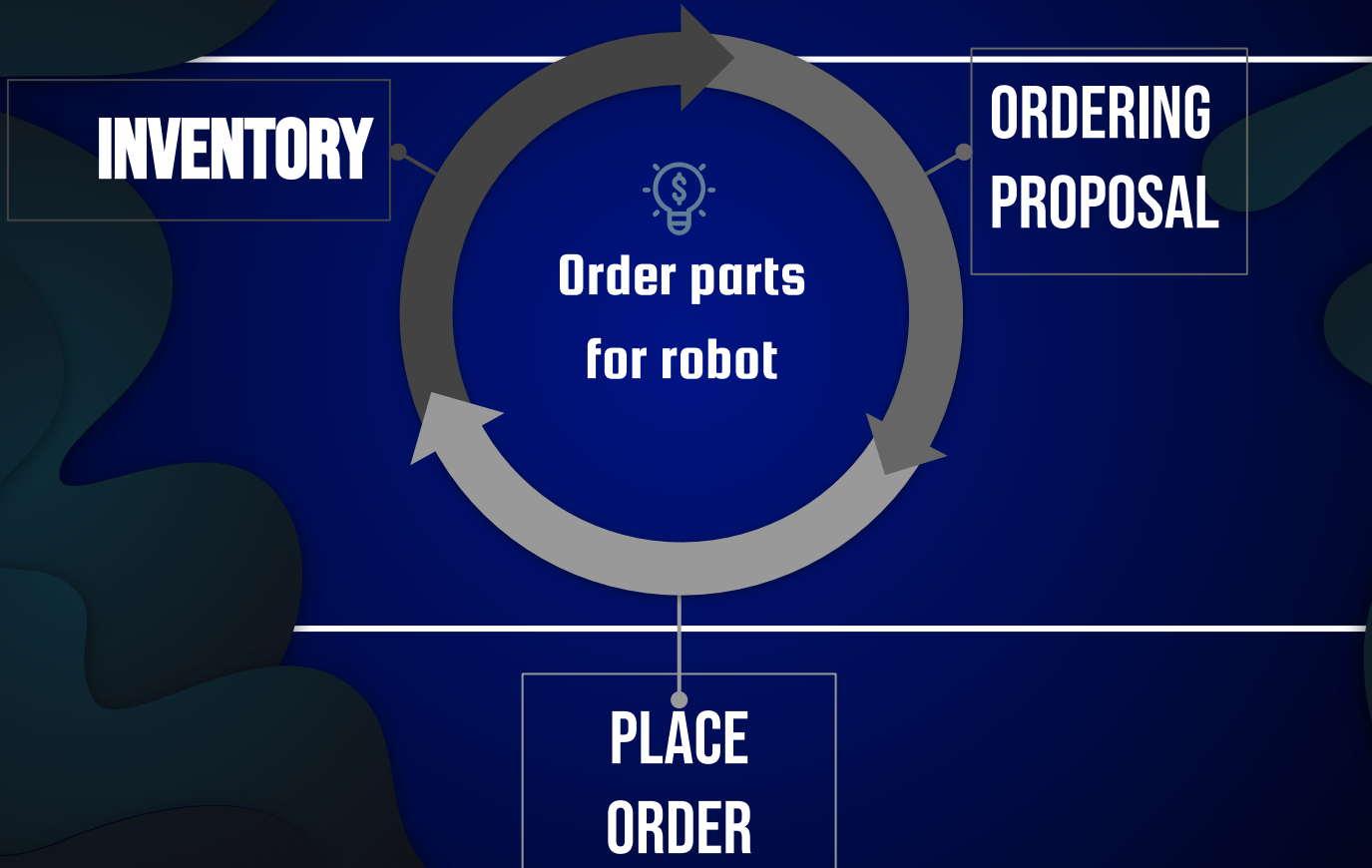
— Everyone



Our Ordering Process

Why do we do this?

Answer? Mentors make us



Inventory

- **Count how many of each component you have (yes this will take a while!)**
 - COUNT CRIMPS
 - WIRE LENGTHS
 - SHIELDING
 - ELECTRONIC COMPONENTS (PDP, PCM, VRM, ETC.)
 - This is usually done after round 1 of FIRST Choice (to see if we can get extra electronics)
- **First Choice**
 - TRY TO GET AS MUCH ON FIRST CHOICE AS POSSIBLE
 - USE THE VENDOR VOUCHERS!
- **Find new Components that are effective for your team**
 - CHECK VENDORS FOR NEW PRODUCTS
 - If you have the opportunity to go to world championships, talk with vendors in person to see if they have anything new for the FRC field.
 - Be sure to check in with teams who have had this opportunity, they may have found some new components.
 - LOOK FOR ALTERNATIVE COMPONENTS

Order proposal to mentors

- **Spreadsheets!**
 - EASILY ACCESSIBLE FOR ALL MENTORS
- **Explain reasoning for your order and why**
 - ARE THERE ANY BETTER DEALS FROM DIFFERENT VENDORS?
 - SHIPPING COST COMPARISON?
 - WHY ARE THEY NECESSARY?
 - Everything on your order should have a justification as to why you're ordering it.
- **Consolidate vendors (to reduce shipping cost)**
 - AFTER COMPARING SHIPPING PRICES
 - AFTER COMPARING THE PRICE OF THE COMPONENT ON DIFFERENT WEBSITES
 - QUANTITY DISCOUNTS (DON'T ORDER 40 WHEN BOX OF 50 IS CHEAPER)

Ordering Spreadsheet

	Description	Link	price (per unit)	Quan on hand	Need	Quan to Order	Price	Amount getting	Cancel?	Pack of #?	ordered from FI In kickoff kit	coupons
Amazon												
	zipties	https://www.ama	\$13	1	1	0	\$0	0		500		
	15mmX30mm cable chain	https://www.ama	\$21	0	3	3	\$63	3		1.00m		
	white sticky squares	https://www.ama	\$6.02	1	2	1	\$6	100		100		
	1" heat shrink for batteries	https://www.ama	\$38.99	1	1	0	\$0	0		100.00ft		
	5V Individually addressable LED lights	https://www.ama	\$32.88	0	2	2	\$66	32.8		16.40ft		
	On / off Switch	https://www.ama	\$31.78	2	3	1	\$32	1		1		
	clear nylon sheathing	https://www.elec	\$0.55	0	25	14.75	\$0	14.75	y	1.00ft		
SHIPPING							\$0					
POST SHIPPING TOTAL							\$0					
CLIPPARD												
11130-Q	1/4in NPT muffler	https://www.clipp	\$3	0	4	4	\$0	4	Y	1		
AVT-12-1	TINY AIR TANK (250psi) 1in cubic volume	https://www.clipp	\$11	0	0	0	\$0	0	Y	1		
VYH1-0804-CI	1/4in Vinyl Tubing	https://www.clipp	\$11	2	2	0	\$0	0.00ft		50.00ft		
PRE-TOTAL							\$0					
SHIPPING							\$15					
VOUCHER							-\$20					
POST SHIPPING TOTAL							-\$5					
CFORCE												
CF011X	Portable monitor	https://cforce.com	\$119	0	0	0	\$0	0	y	1		
CABLE TIES & MORE												
BSSCE1.00-25	nylon openable sleeve	https://www.cabl	1.32	25.00ft	25.00ft	0.00ft	\$0	0		1		
SUPER BRIGHT LEDs												
AE70-GCOB	70mm light ring green	https://www.supe	\$2.88	1	2	1	\$0	1	y	1		

“So the [roborio] has to move... again...”

— **4499's Electrical Team**

“So the [compressor] has to move... again...”

— **4499's Electrical Team**

“So the [router] has to move... again...”

— **4499's Electrical Team**

“So the [air tank] has to move... again...”

— **4499's Electrical Team**

“So the [camera] has to move... again...”

— **4499's Electrical Team**

Team Practices

Electronic

Crimping

**Board
Design/Fabrication**

**Mounting/securing
components/Assembly**

Sensors

CAD/ Design

Pneumatics

Crimping



- **Standardized instructions for crimping**
 - **OUR TEAM USES A “FORMULA” WHEN USING OUR CRIMPS.**
 - This means a type of connector should be crimped the same way every time so they can be interchangeable with other cables.
- **Use the proper crimps for the connector you’re using**
 - Pliers, vices, and hammers will never give you the quality connection given when you use the proper crimper.

Board Design/Fabrication



Material

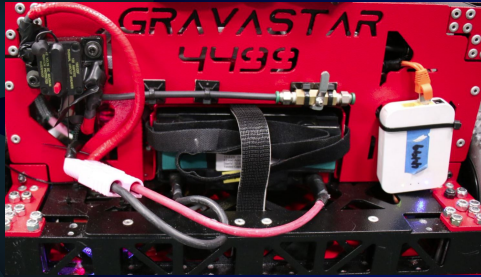
- Aluminum Sheets
- Carbon Fiber (careful it conducts electricity)
- Corkboard

Covers

- Lexan
- Aluminum



Mounting/ Securing Components



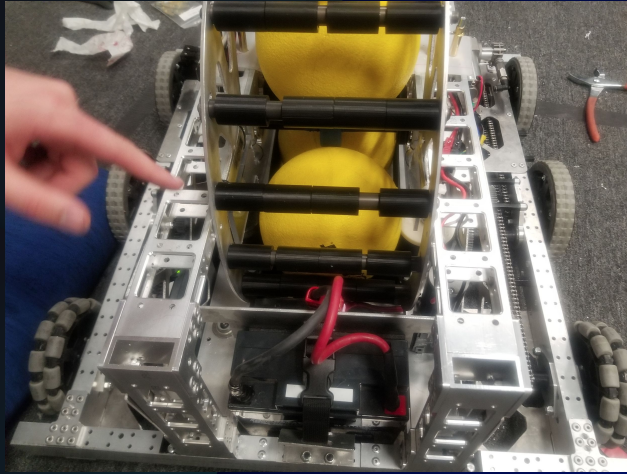
- When zip-tying cables down, do not put too much strain on them. Over time this can cause shearing and disconnection issues.
- Cable tie mounts are used when there is no other mounting solution
- Double sided sticky tape is used for vibration dampening and extra security on components

Mounting batteries:

- Vertical mounts result in less dropped batteries on the field (from our experience)
- Use either an elastic band or buckle to secure the battery in place.
- *We have learned this the hard way a few too many times.*



Sensors



Plan

- **Make a plan on location**
 - WHERE DO THE SENSORS NEED TO COMMUNICATE INFORMATION FROM?
 - e.g. Telling how many game elements you're currently holding and where they are.
- **How are wires run to the sensor**
 - HOW MANY WIRES DOES IT NEED?
 - Is it like a beam break, where it's like two sensors?
 - WHAT SIGNAL TYPE IS THE SENSOR?
 - PWM, DIO, Analog, Relay?
- **How long will the wires need to be?**
 - IF THE SENSOR IS ON A MOVING COMPONENT, BE SURE TO GIVE SOME SLACK TO THE WIRE (SO IT CAN ACTUALLY MOVE)
- **Label your sensor cables**
 - USUALLY WITH COLORED ELECTRICAL TAPE.

Rigid mounting solutions

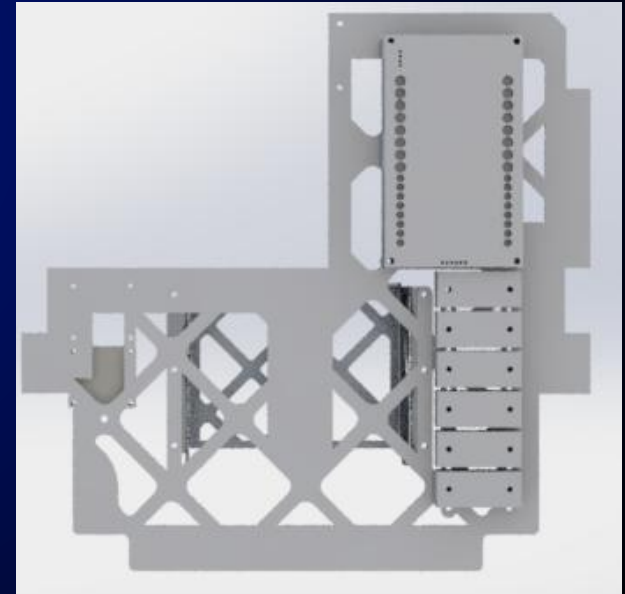
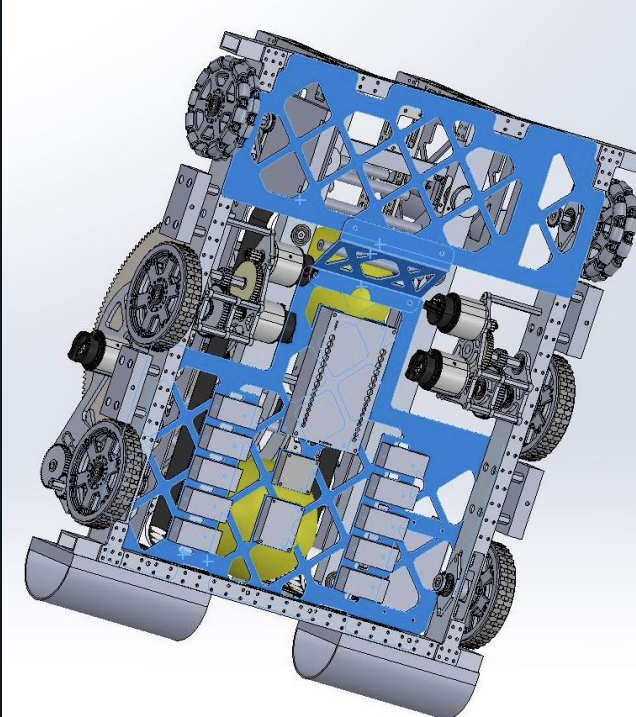
- Limit switches - add hardstops
- Camera mounts
- Light ring



CAD/Design

Solidworks

- We don't design wires since it is tricky and time consuming
- Linear/Circular sketch pattern to create lattice
- Very simple boxes that represent components, allow for less rendering, and easier CAD instead of using complicated 3D models.



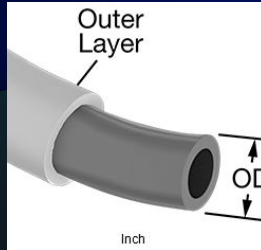
Pneumatics

How we mount pneumatics

- **Avoid sharp turns**
 - PNEUMATIC TUBING TENDS TO NOT PERFORM TOO WELL WHEN BENT TOO MUCH.
 - Ask yourself, where are the tightest corners of my tubing (those are likely to be failure points)

What do we use?

- **NOT JUST 1/4IN TUBING**
 - For components such as a pancake piston with not much stroke, we use 1/8in tubing.
- **QUALITY FITTINGS**
 - McMaster and Automation direct have some very high quality fittings that we use.
- **QUALITY TUBING**
 - The tubing we use from McMaster is abrasion resistant, and allows a much tighter grip when put into PTC fittings.



“Howdy!”

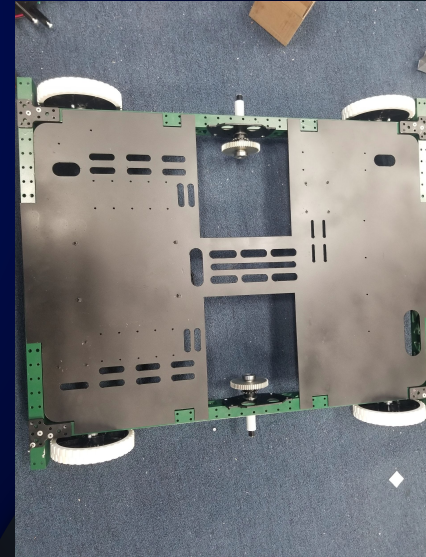
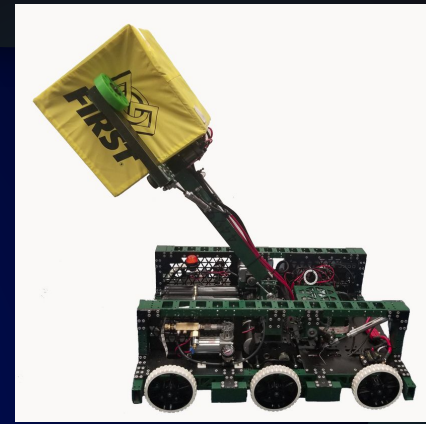
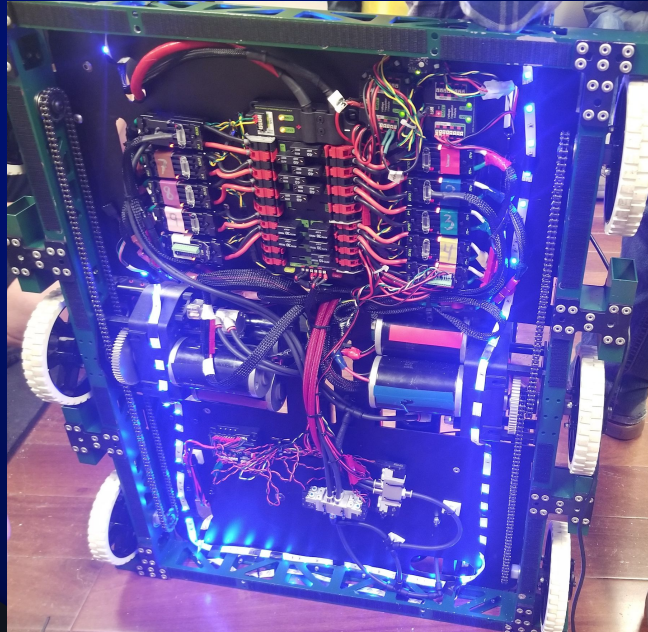
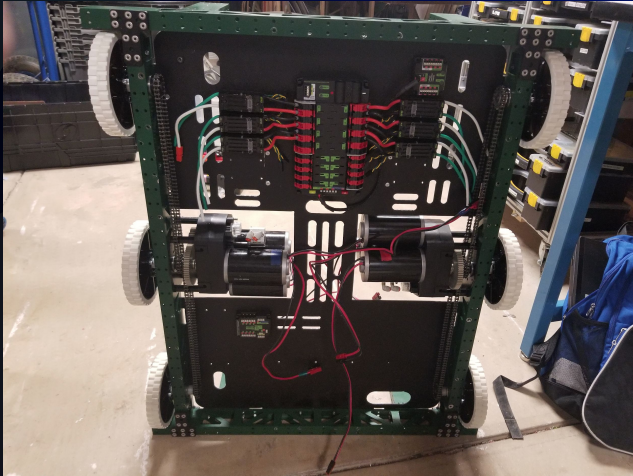
— **Jack Herlihy**

սնչաբ
ստոր էրիսոն



2018 robot

- Simplistic Design lended to more space to be utilized
- First year of upside down electronics
- Easy communication between Mechanical and Electrical
- Quick Maintenance
- Components and wires safely secured

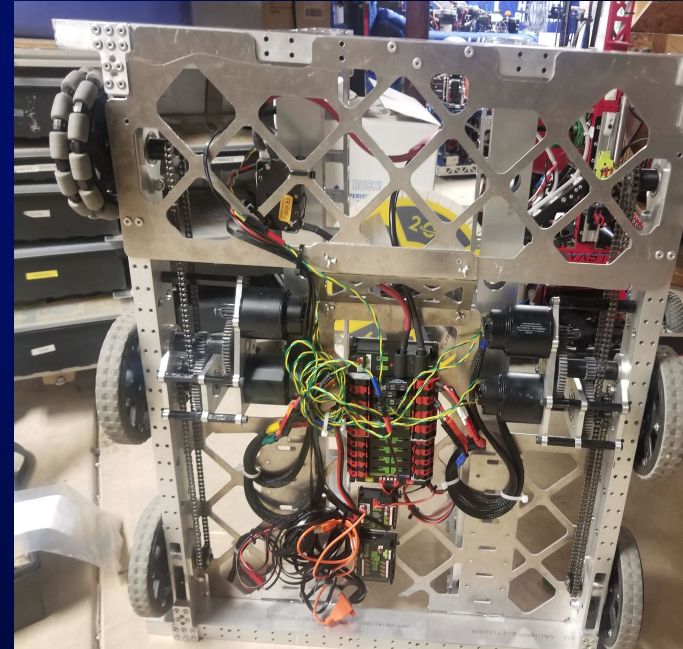
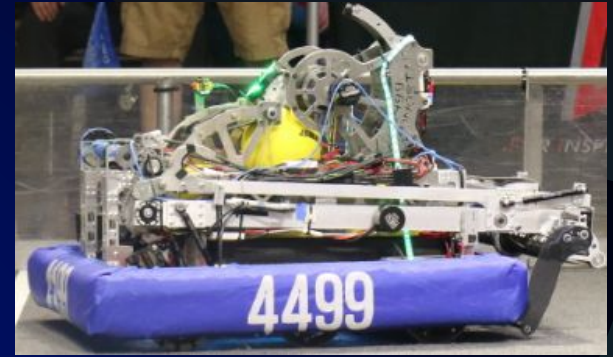
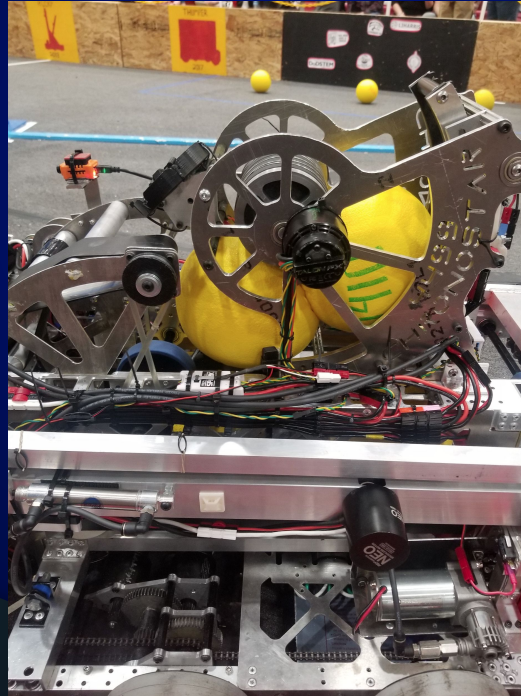
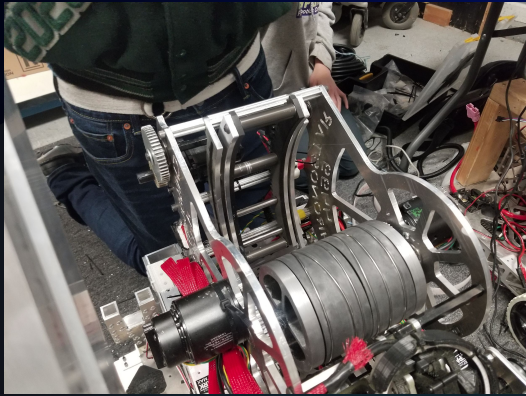


2020 robot

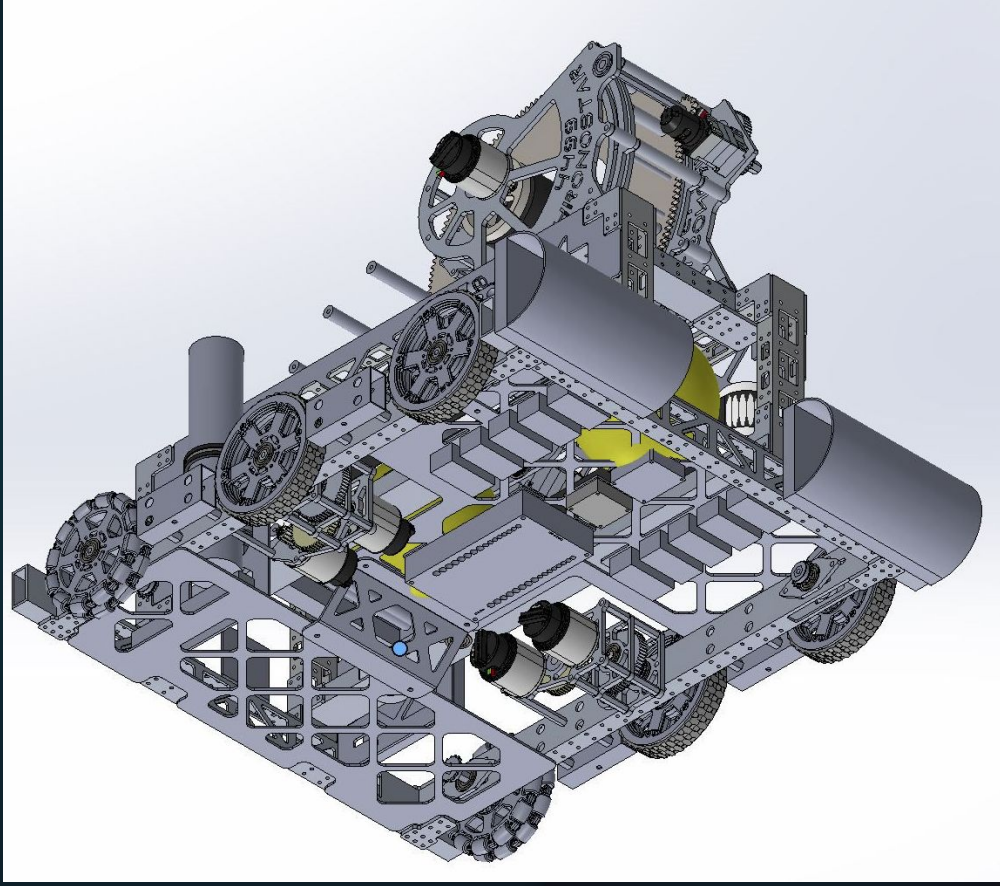
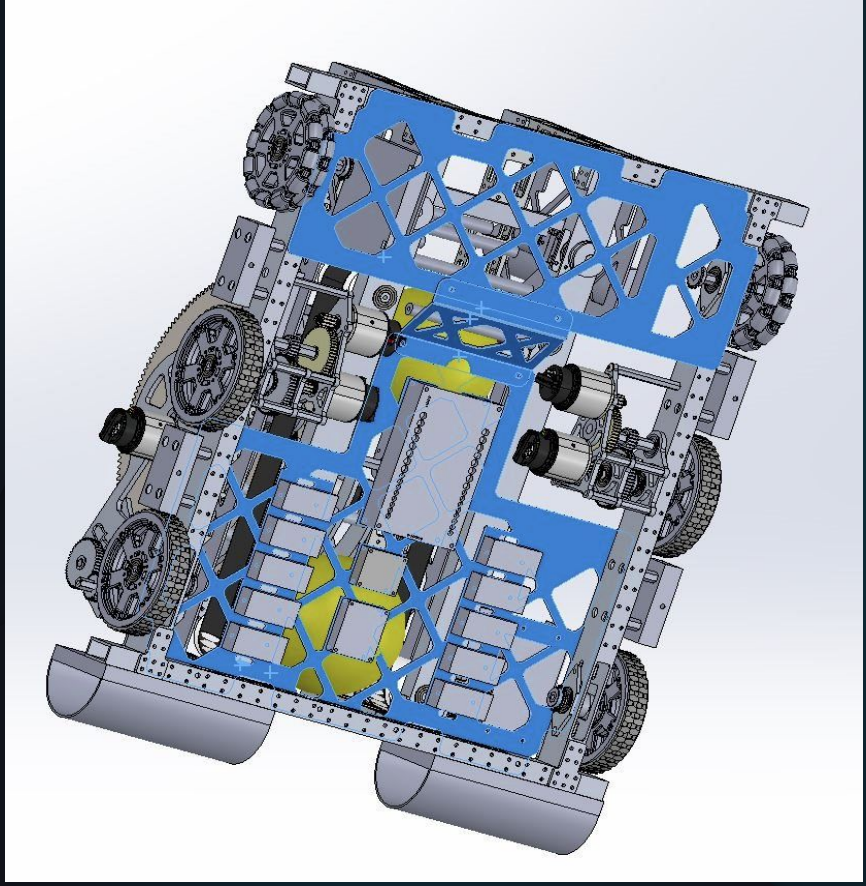
- Rapid Changes lead to redesign
- Limited space due to complexity of robot
 - Manageability issues
 - Robot design constraints

Improvements?

- Group of wires
- stand-offs
- adjustable camera mount

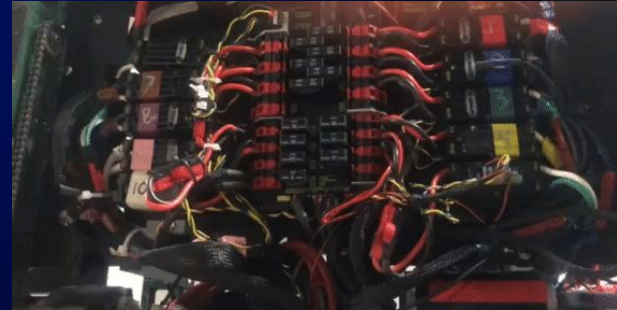


2020 Robot CAD Design



Generic Upside down Design Tips

- Use a **removable cover** on the bottom of your robot to protect vital components
 - This cover should also preferably be clear, so you can see signal lights to troubleshoot issues without taking the cover off.
- Assemble components before mounting board to robot
- Certain components need to be visible (RoboRIO, RSL, etc.)
- Certain components may be too big to fit underneath
- Add access points for wires to reach to mechanisms



“Are you freaking kidding me right now Cooper?”

— **Alex Torres**

Troubleshooting



How to troubleshoot quickly?

- **Identify what specifically is “broken”**
 - What components could be the issue?
 - Is it actually an electrical problem?
- **Voltmeter**
 - Check if grounded to frame
 - Continuity between wires
 - Check if voltage is passing through wires
- **Process of Elimination**
 - Individually verify each component is working correctly in a chain of relying components





“HEY! Safety glasses!”

— Hailey Holman

Lessons learned



Communication is KEY

Test every connection after a match

Never assume a wire/crimp will last forever

Expect a lot of unplugging and replugging from the RoboRIO (use ethernet and USB extenders for more accessibility, and so the ports don't break)

Make spare cables, especially the ones that are hard to make.

References

Tool/Item	Website	Picture
Powerpole Crimper	Amazon	 A pair of red-handled crimpers with black jaws, used for crimping Powerpole connectors.
Battery Crimper	Amazon	 A yellow and black crimping tool with a red carrying case and several metal ferrules.
Crimper for ferrules	Amazon	 A pair of orange-handled crimpers with silver metal jaws, designed for crimping ferrules.
Precision Microfit Crimper	Amazon	 A pair of orange-handled crimpers with black jaws, used for precision crimping.
Pneumatic tubing cutters	Automation Direct	 A blue pneumatic tubing cutter with a silver cutting wheel and a label 'TC-12'.

[Supplies and Components](#)



Our commonly used electrical supply list

Questions